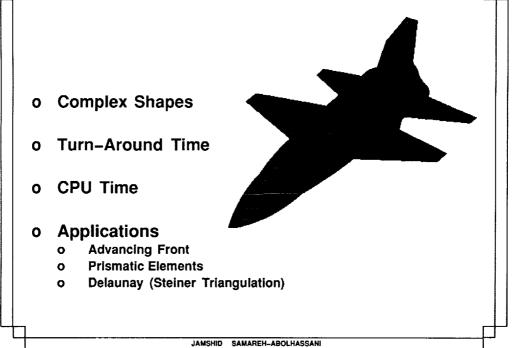
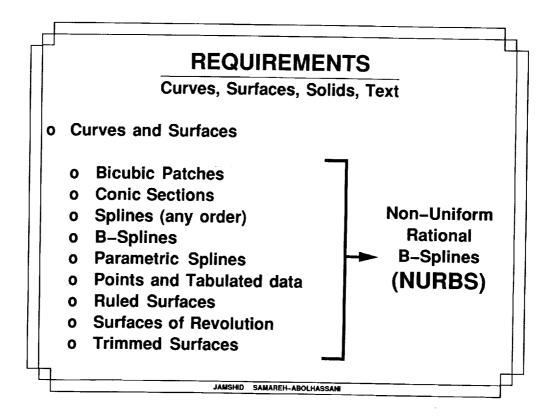
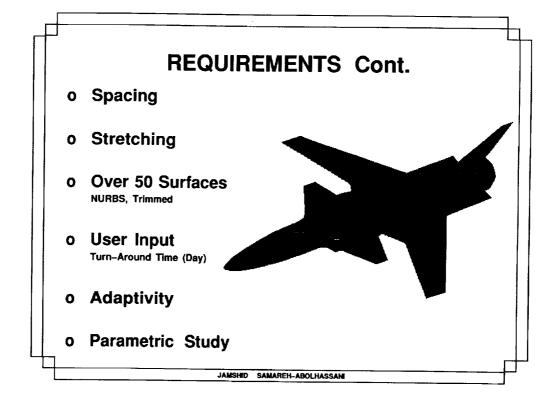
UNSTRUCTURED SURFACE GRID GENERATION

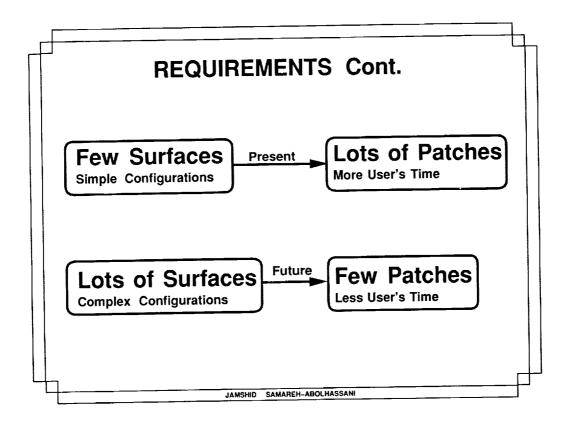
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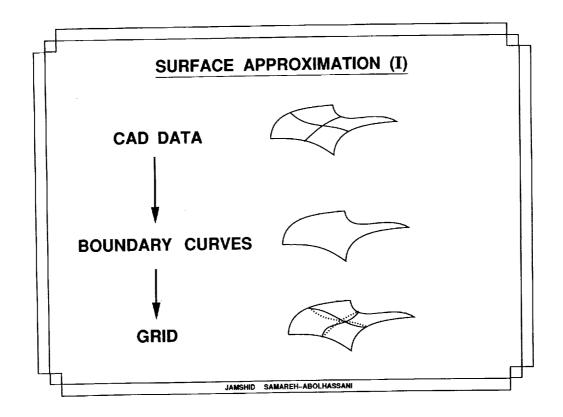
- o INTRODUCTION
- o **REQUIREMENTS**
- o SURFACE APPROXIMATIONS
- o METHODS
- o GEOLAB EFFORT

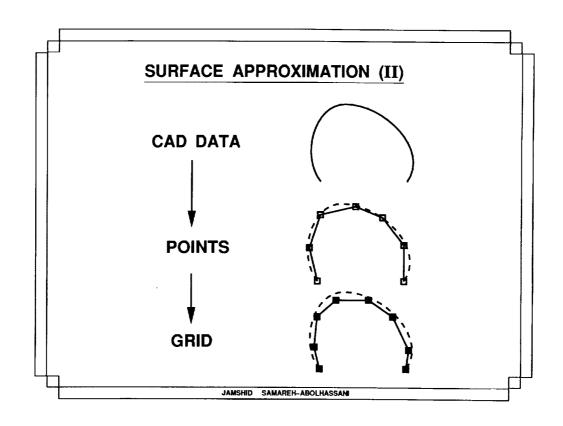


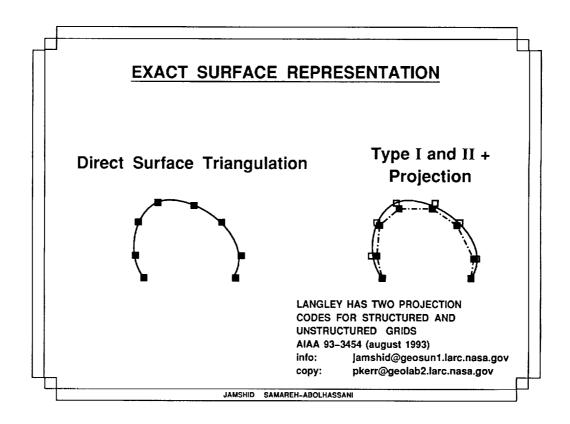


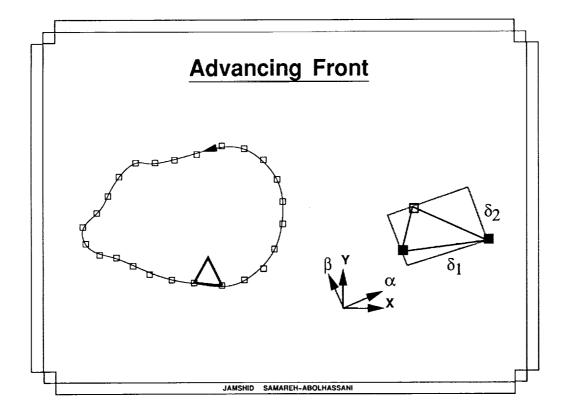






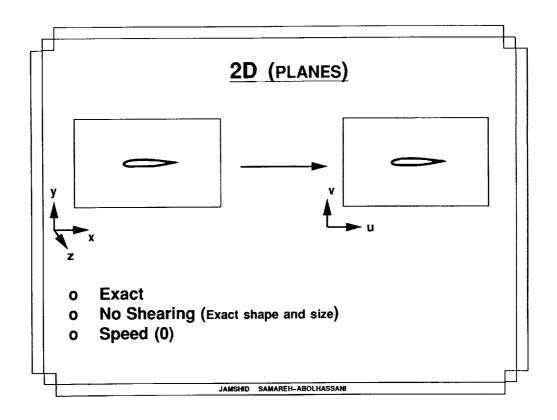


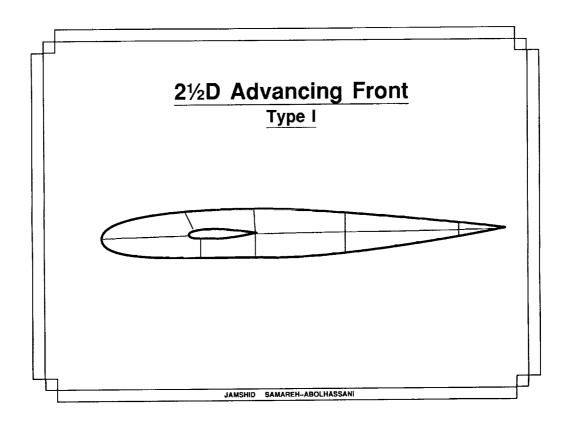


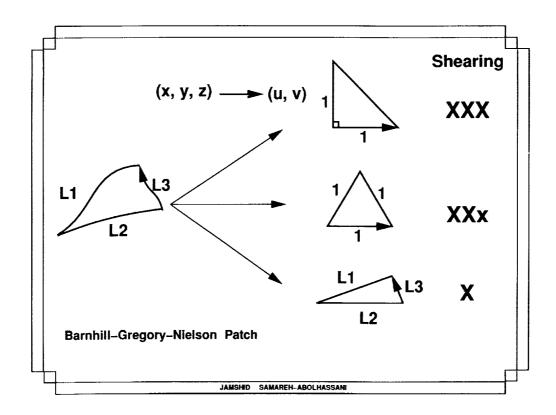


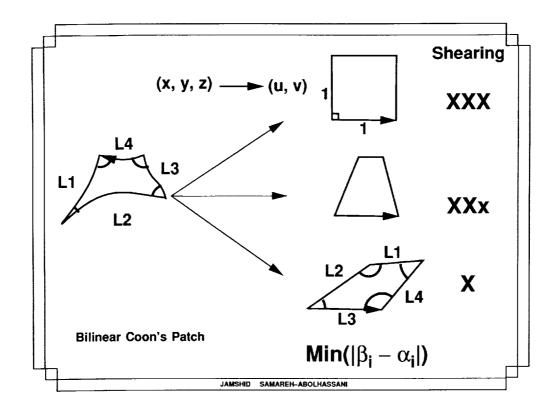
METHODS

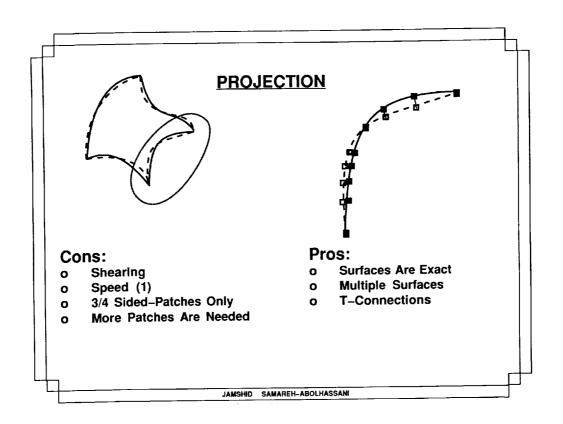
- o 2D (Planes, Triangulation is performed in the parameter space)
- o 2 1/2 D (Triangulation is performed in the Parameter Space)
- o 3D (Triangulation is performed in the Physical and Parameter Spaces)

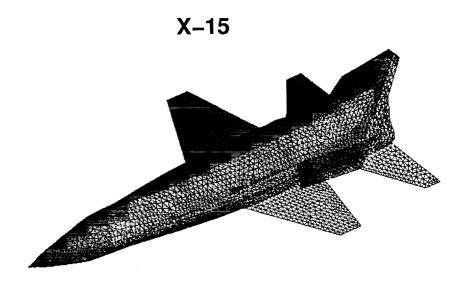


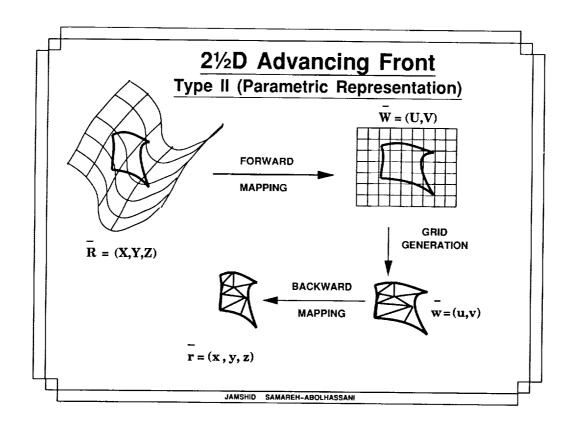


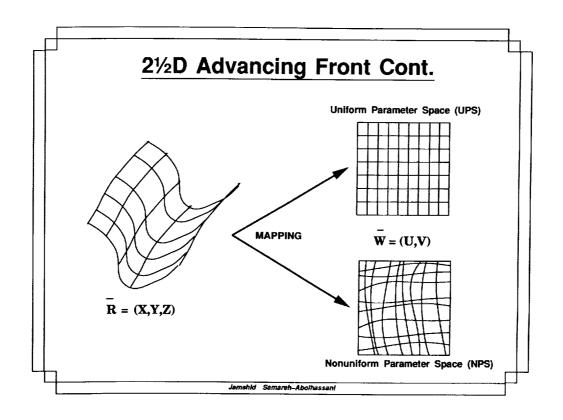


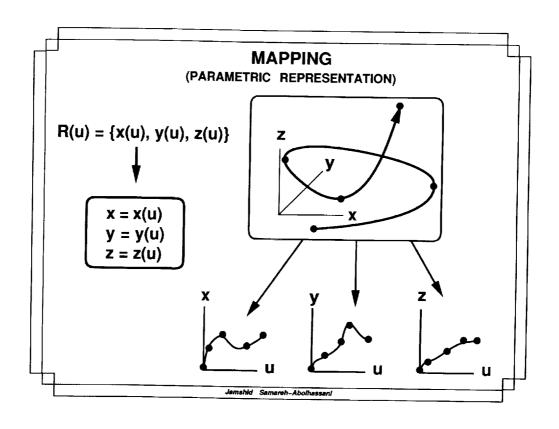


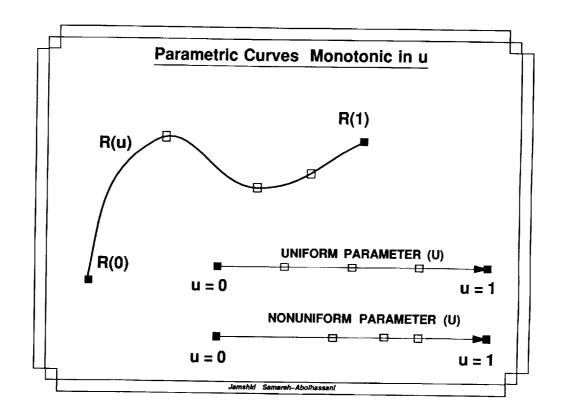


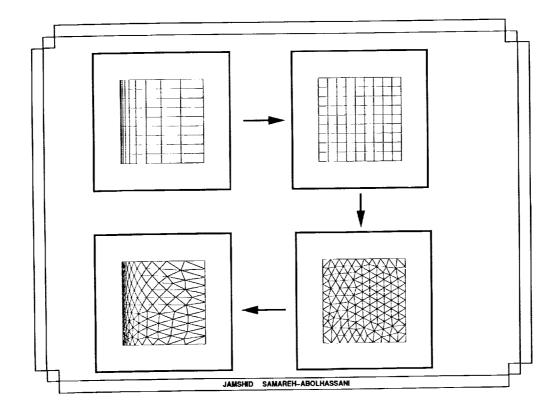


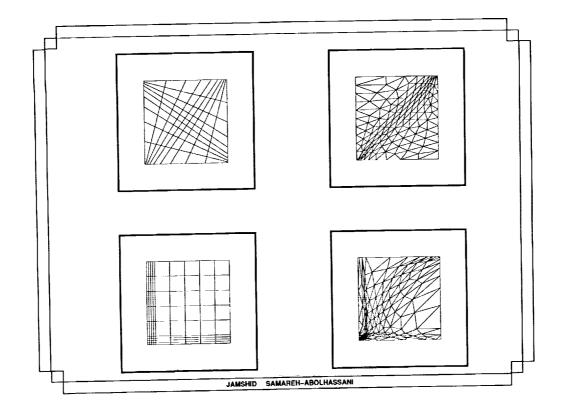


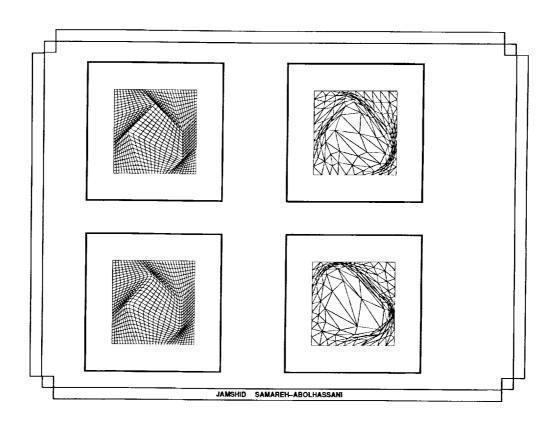


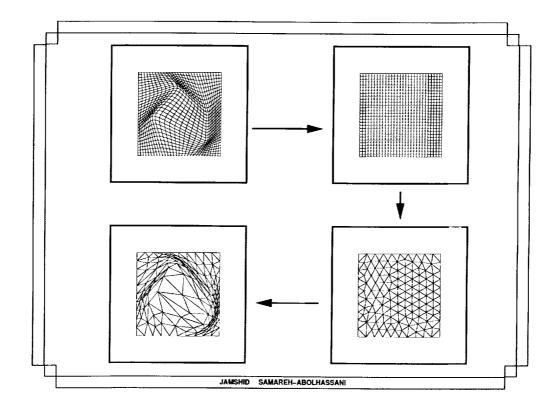


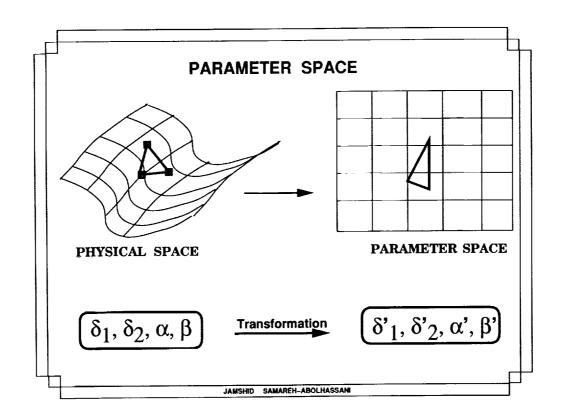


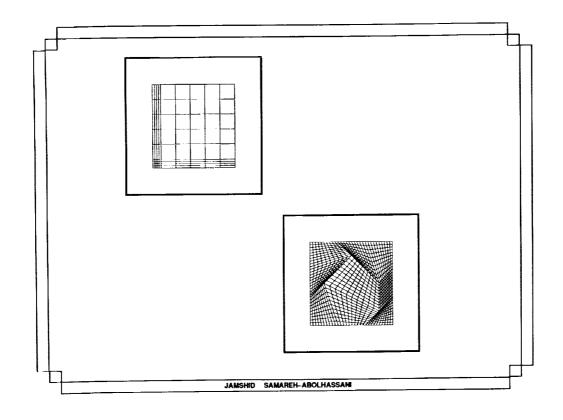


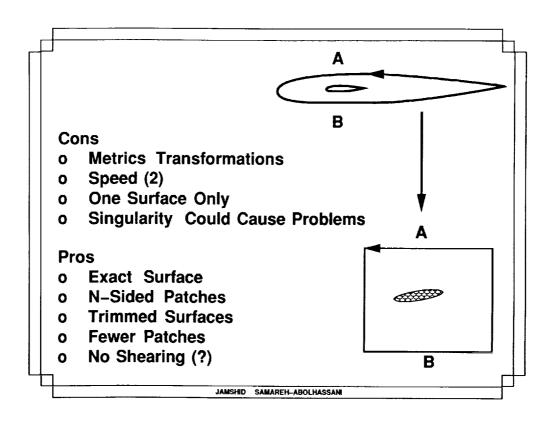


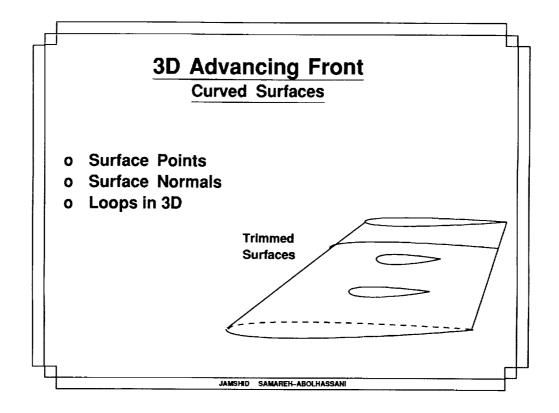


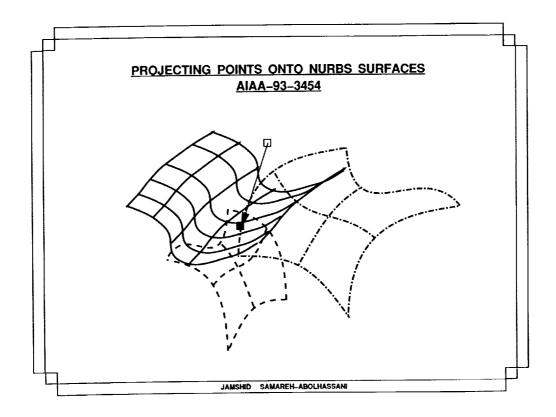


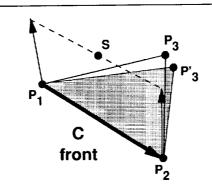












Steps:

- 1. Compute a plane normal to (P₁, P₂, S)
- 2. Generate a New Point (P'3) on the Plane (Spacing and Stretching)
- 3. Project Point (P'3) onto the Appropriate Surfaces
- 4. Compute a Plane Based on (P₁, P₂, P'₃)
- 5. Repeat Steps 2-4 Till Changes in P'3 Are Very Small

3D Advancing Front

Curved Surfaces

Cons:

- o Surface Normals Are Required
- o Projection Is Required
- o Trimmed Surfaces
- o Speed (4)

Pros:

- o Triangulation Is Performed in the Physical Space
- o No Shearing Due Parameter Space
- o Metric Transformation Is not Needed
- o N-Sided Patches with With Multiple Loops
- o Multiple Surfaces
- o Fewer Patches

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	2D	Type I 2½ D	Type I 2½DP	Type 2 2½ D	3D
User Input Factor(# of Patches)	1	4	4	3	2
CPU Time Factor	1	2	3	4	5
Surface Types	P	NA	NURBS	NURBS	NURBS
Surface Accuracy	good	poor	Good	Good	Good
$\delta,lpha,eta$ Transformation	simple	simple	simple	Difficult	NA
Problems With Shearing	None	Yes	Yes	Possible	None
Parametric Study	0	0	2	3	3
Number of Surfaces	NA	Many	Many	One	Many
N-Sided Patches Possible	Yes	No	No	Yes	Yes
Problems with Singularity	No	No	Yes	Yes	Yes
Surface Normals Required	No	No	No	No	Yes
History	4	3	3	1	0

CSC/GEOLAB/TAB EFFORT

- o NURBS Based (IGES, NASA IGES)
 - o NURBS Surfaces
 - o NURBS Curves
 - o Trimmed Surfaces
- o Points (network)
- o Single Interactive Interface
- o Surface Grid Generation
 Based on 3D Advancing Front
- o Projection

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STEPS

- o STEP 1 POINTS/CURVES/PATCHES
 - o allowing for future additions
 - o Surface (points)
 - o create points/curves/patches for vgrid3d (or other systems)
- o STEP 2 Background Grid
- o STEP 3 PROJECTION/SMOOTHING/QUALITY CHECK
- o STEP 4 ADD SURFACE GRID GENERATION (Direct Surface Triangulation)
- o STEP 5 MOTIF / X BASED (other platform)

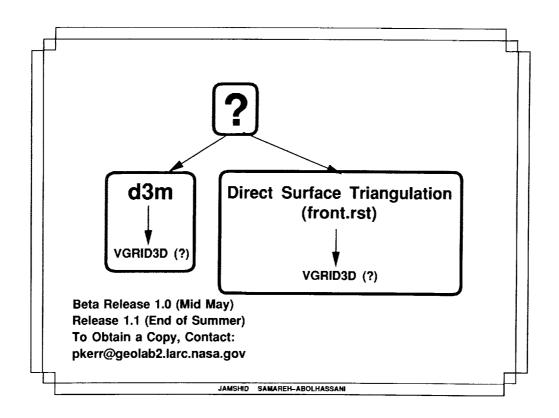
1/0

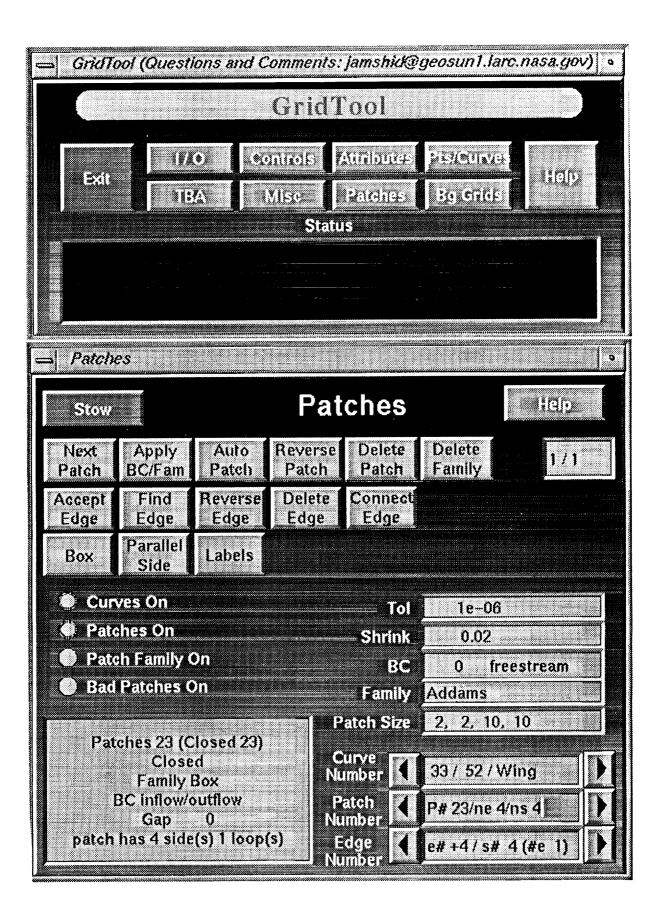
	INPUT ASCII	INPUT Binary	OUTPUT ASCII	OUTPUT Binary
Restart	х	???	X	???
HESS	x	NA	X	NA
D3M	x	NA	X	NA
GRIDGEN	x	x	X	x
PLOT3D	x	х	X	x
LaWGS	X	NA	X	NA
			^	
IGES-128	X	NA		

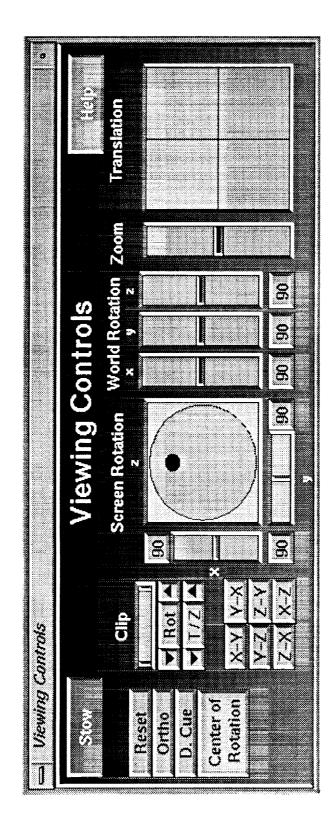
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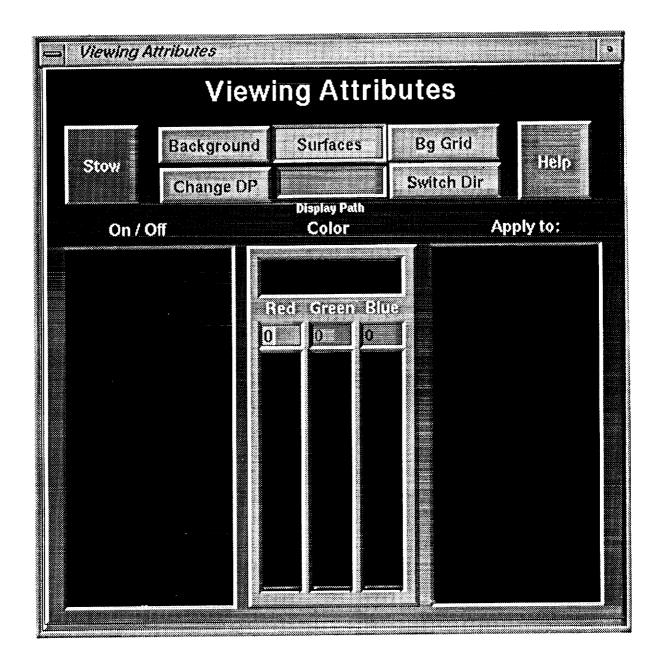
SURFACES

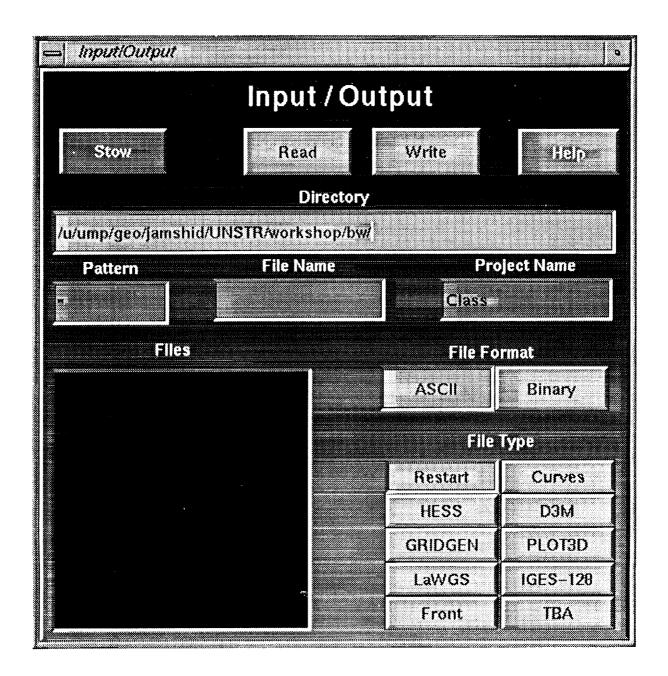
- o NURBS (NonUniform Rational B-Spline)
- o Converts hess, gridgen, plot3d, lawgs to equivalent NURBS surfaces
- o Defined everywhere
- o Display Path (write the grid out)

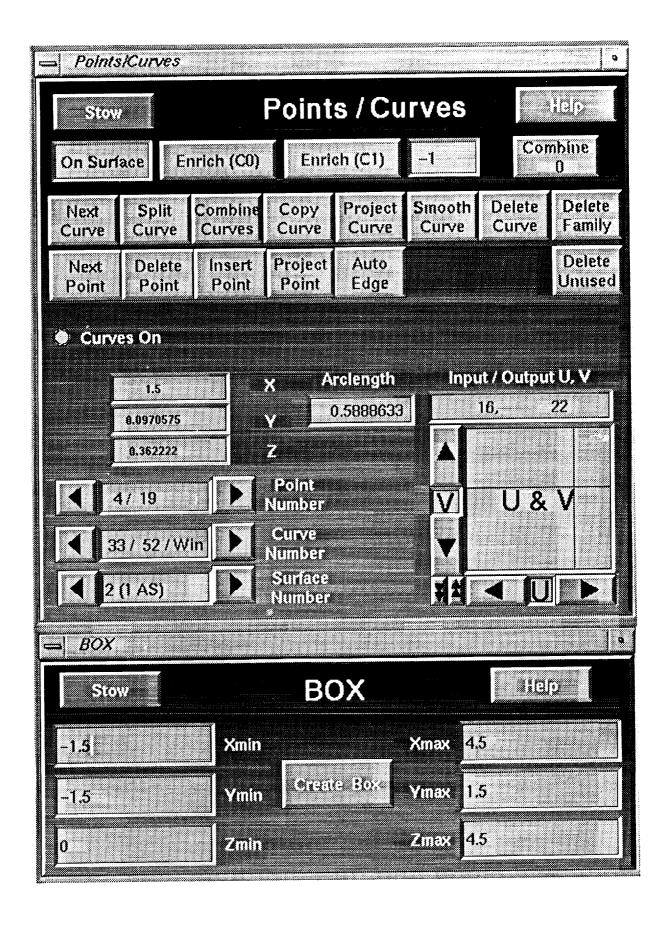


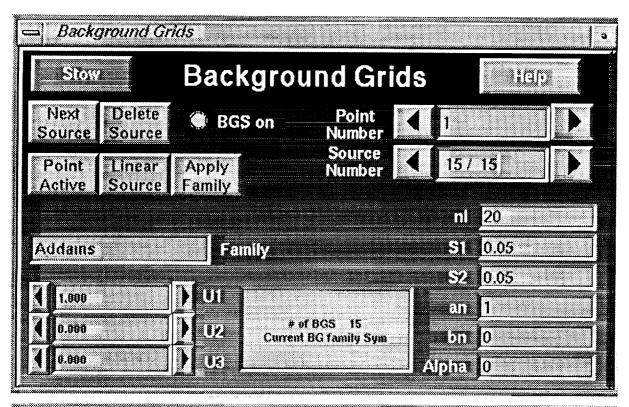


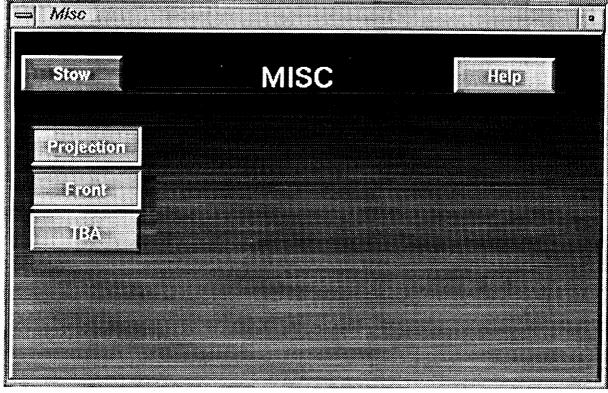


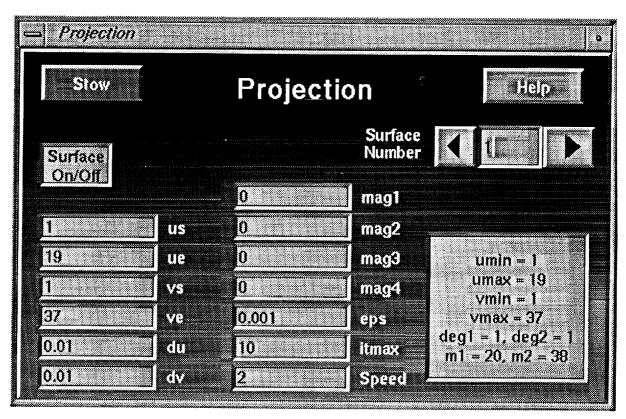


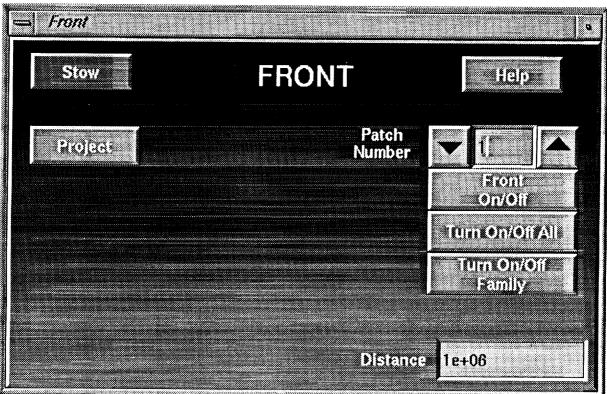












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